

Chapter 6

Lecture 2

Canonical Transformations

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6.1 Canonical Transformations

Properties of the Four basic canonical transformations

Generating function	Derivatives of generating function	Trivial special cases	Transformation
$F_1(q_i, Q_i, t)$	$p_i = \frac{\partial F_1}{\partial q_i}, P_i = -\frac{\partial F_1}{\partial Q_i}$	$F_1 = q_i Q_i$	$p_i = Q_i,$ $P_i = -q_i$
$F_2(q_i, P_i, t)$	$p_i = \frac{\partial F_2}{\partial q_i}, Q_i = \frac{\partial F_2}{\partial P_i}$	$F_2 = q_i P_i$	$p_i = P_i$ $Q_i = q_i$
$F_3(p_i, Q_i, t)$	$q_i = -\frac{\partial F_3}{\partial p_i}, P_i = -\frac{\partial F_3}{\partial Q_i}$	$F_3 = p_i Q_i$	$q_i = -Q_i$ $P_i = -p_i$
$F_4(p_i, P_i, t)$	$q_i = -\frac{\partial F_4}{\partial p_i}, Q_i = \frac{\partial F_4}{\partial P_i}$	$F_4 = p_i P_i$	$q_i = -P_i$ $Q_i = p_i$

6.2 Conditions for the transformation to be canonical

Conditions for the transformation to be canonical

For $F_1(q_i, Q_i, t) \Rightarrow dF_1 = \sum p_i dq_i - \sum P_i dQ_i$

For $F_2(q_i, P_i, t) \Rightarrow dF_2 = \sum p_i dq_i + \sum Q_i dP_i$

For $F_3(p_i, Q_i, t) \Rightarrow dF_3 = -\sum q_i dp_i - \sum P_i dQ_i$

For $F_4(p_i, P_i, t) \Rightarrow dF_4 = -\sum q_i dp_i + \sum Q_i dP_i$

6.2 Conditions for the transformation to be canonical

The transformation from (q_i, p_i) to (Q_i, P_i) will be canonical if

$$\sum p_i dq_i - \sum P_i dQ_i$$

is an exact differential

Solution: Consider the generating function $F_1(q_i, Q_i)$

$$dF_1 = \sum \frac{\partial F_1}{\partial q_i} dq_i + \sum \frac{\partial F_1}{\partial Q_i} dQ_i$$

Since $p_i = \frac{\partial F_1}{\partial q_i}$ and $P_i = -\frac{\partial F_1}{\partial Q_i}$

Therefore,

$$dF_1 = \sum p_i dq_i - \sum P_i dQ_i$$

which is an exact differential equation.

6.2 Conditions for the transformation to be canonical

Similarly, considering generating function $F_4(p_i, P_i, t)$

$$dF_4(p_i, P_i, t) = \sum \frac{\partial F_4}{\partial p_i} dp_i + \sum \frac{\partial F_4}{\partial P_i} dP_i$$

Since $q_i = -\frac{\partial F_4}{\partial p_i}$ and $Q_i = \frac{\partial F_4}{\partial P_i}$

Therefore, $dF_4(p_i, P_i, t) = -\sum q_i dp_i + \sum Q_i dP_i$ which is an exact differential

Now subtracting dF_4 from dF_1

$$\begin{aligned} dF_1 - dF_4 &= \sum p_i dq_i - \sum P_i dQ_i + \sum q_i dp_i - \sum Q_i dP_i \\ \Rightarrow dF_1 - dF_4 &= (\sum q_i dp_i + \sum p_i dq_i) - (\sum Q_i dP_i + \sum P_i dQ_i) \end{aligned}$$

6.2 Conditions for the transformation to be canonical

$$\Rightarrow dF_1 - dF_4 = d(q_i p_i) - d(Q_i P_i)$$

$$\Rightarrow d(F_1 - F_4) = d(q_i p_i - Q_i P_i)$$

Which is exact differential. Therefore the transformation is canonical.

And $\Rightarrow F_1 = F_4 + q_i p_i - Q_i P_i$

Examples [Conditions for the transformation to be canonical]

Show that transformation

$$P = \frac{1}{2}(p^2 + q^2) \text{ and } Q = \tan^{-1} \frac{q}{p}$$

Solution: The transformation is canonical if $[pdq - PdQ]$ is an exact differential

$$pdq - PdQ = pdq - \frac{1}{2}(p^2 + q^2) \left[\frac{pdq - qdp}{p^2} \right]$$

$$\Rightarrow pdq - PdQ = pdq - \frac{1}{2}(p^2 + q^2) \left[\frac{pdq - qdp}{p^2} \times \frac{p^2}{p^2 + q^2} \right]$$

$$\Rightarrow pdq - PdQ = pdq - \frac{1}{2}[pdq - qdp]$$

Examples [Conditions for the transformation to be canonical]

$$\Rightarrow pdq - PdQ = \frac{1}{2}pdq + \frac{1}{2}qdp$$

$$\Rightarrow pdq - PdQ = \frac{1}{2}(pdq + qdp)$$

$$\Rightarrow pdq - PdQ = \frac{1}{2}d(pq)$$

Hence the transformation is canonical.

Second Approach

Symplectic approach to canonical transformation

Let

$$Q_i = Q_i(q_j, p_j)$$
$$P_i = P_i(q_j, p_j)$$

The inverse transformation are

$$q_j = q_j(Q_i, P_i)$$
$$p_j = p_j(Q_i, P_i)$$

As the transformation does not involve time, therefore the Hamiltonian does not change in this case.

$$K(Q_i, P_i) = H(q_j, p_j)$$

To verify

$$\dot{Q}_i = \frac{\partial K}{\partial P_i} = \frac{\partial H}{\partial P_i}$$

We Know that

$$H = H(q_j, p_j)$$

$$\frac{\partial H}{\partial P_i} = \sum_j \frac{\partial H}{\partial q_j} \frac{\partial q_j}{\partial P_i} + \sum_j \frac{\partial H}{\partial p_j} \frac{\partial p_j}{\partial P_i} \quad (1)$$

Second Approach

Now

$$\begin{aligned}\dot{Q}_i &= \sum_j \frac{\partial Q_i}{\partial q_j} \dot{q}_j + \sum_j \frac{\partial Q_i}{\partial p_j} \dot{p}_j \\ \Rightarrow \dot{Q}_i &= \sum_j \frac{\partial Q_i}{\partial q_j} \frac{\partial H}{\partial p_j} - \sum_j \frac{\partial Q_i}{\partial p_j} \frac{\partial H}{\partial q_j}\end{aligned}\quad (2)$$

Comparing eq (1) and eq (2) we concludes that

$$\dot{Q}_i = \frac{\partial H}{\partial P_i}$$

The transformation is **Canonical** only if

$$\left(\frac{\partial Q_i}{\partial q_j}\right)_{q_j, p_j} = \left(\frac{\partial p_j}{\partial P_i}\right)_{Q_i, P_i} \quad \text{and} \quad \left(\frac{\partial Q_i}{\partial p_j}\right)_{q_j, p_j} = -\left(\frac{\partial q_j}{\partial P_i}\right)_{Q_i, P_i}$$

Similarly we verify

$$\dot{P}_i = -\frac{\partial H}{\partial Q_i}$$

Second Approach

$$\frac{\partial H}{\partial Q_i} = \sum_j \frac{\partial H}{\partial q_j} \frac{\partial q_j}{\partial Q_i} + \sum_j \frac{\partial H}{\partial p_j} \frac{\partial p_j}{\partial Q_i} \quad (3)$$

and

$$\dot{P}_i = \sum_j \frac{\partial P_i}{\partial q_j} \dot{q}_j + \sum_j \frac{\partial P_i}{\partial p_j} \dot{p}_j$$

$$\Rightarrow \dot{P}_i = \sum_j \frac{\partial P_i}{\partial q_j} \frac{\partial H}{\partial p_j} - \sum_j \frac{\partial P_i}{\partial p_j} \frac{\partial H}{\partial q_j} \quad (4)$$

Comparing eq (3) and eq (4) we concludes that

$$\dot{P}_i = -\frac{\partial H}{\partial Q_i}$$

The transformation is Canonical only if

$$\left(\frac{\partial P_i}{\partial p_j}\right)_{q_j, p_j} = \left(\frac{\partial q_j}{\partial Q_i}\right)_{Q_i, P_i} \quad \text{and} \quad \left(\frac{\partial P_i}{\partial q_j}\right)_{q_j, p_j} = -\left(\frac{\partial p_j}{\partial Q_i}\right)_{Q_i, P_i}$$

Examples

Show that transformation

$$Q = \log\left(\frac{1}{q} \sin p\right) \text{ and } P = q \cot p$$

Solution: since

$$Q = \log\left(\frac{1}{q} \sin p\right)$$

$$\Rightarrow \dot{Q} = \frac{q}{\sin p} \frac{d}{dt} \left(\frac{1}{q} \sin p\right)$$

$$\Rightarrow \dot{Q} = \frac{q}{\sin p} \left[\frac{q\dot{p} \cos p - \dot{q} \sin p}{q^2} \right]$$

$$\Rightarrow \dot{Q} = \frac{\dot{p} \cos p}{\sin p} - \frac{\dot{q}}{q}$$

$$\Rightarrow \dot{Q} = \dot{p} \cot p - \dot{q} \frac{1}{q}$$

$$\Rightarrow \dot{Q} = -\frac{\partial H}{\partial q} \cot p - \frac{\partial H}{\partial p} \frac{1}{q}$$

Examples

$$\Rightarrow \dot{Q} = \left(-\cot p \frac{\partial P}{\partial q} \right) \frac{\partial H}{\partial P} - \frac{1}{q} \frac{\partial H}{\partial P} \frac{\partial P}{\partial p}$$

$$\Rightarrow \dot{Q} = (-\cot^2 p) \frac{\partial H}{\partial P} - \frac{1}{q} \frac{\partial H}{\partial P} (-q \operatorname{cosec}^2 p)$$

$$\Rightarrow \dot{Q} = (\operatorname{cosec}^2 p - \cot^2 p) \frac{\partial H}{\partial P}$$

$$\Rightarrow \dot{Q} = \frac{\partial H}{\partial P} \quad (1)$$

Now

$$P = q \cot p$$

$$\Rightarrow \dot{P} = \dot{q} \cot p - q \dot{p} \operatorname{cosec}^2 p$$

$$\Rightarrow \dot{P} = \frac{\partial H}{\partial p} \cot p + q \operatorname{cosec}^2 p \frac{\partial H}{\partial q}$$

$$\Rightarrow \dot{P} = \frac{\partial H}{\partial Q} \frac{\partial Q}{\partial p} \cot p + q \operatorname{cosec}^2 p \frac{\partial H}{\partial Q} \frac{\partial Q}{\partial q}$$

Examples

$$\Rightarrow \dot{P} = \frac{\partial H}{\partial Q} \left(\frac{q \cos p}{\sin p \ q} \right) \cot p + q \operatorname{cosec}^2 p \frac{\partial H}{\partial Q} \left(-\frac{q \sin p}{\sin p \ q^2} \right)$$

$$\Rightarrow \dot{P} = \frac{\partial H}{\partial Q} (\cot p) \cot p - \operatorname{cosec}^2 p \frac{\partial H}{\partial Q} (-1)$$

$$\Rightarrow \dot{P} = \frac{\partial H}{\partial Q} \cot^2 p - \operatorname{cosec}^2 p \frac{\partial H}{\partial Q}$$

$$\Rightarrow \dot{P} = \frac{\partial H}{\partial Q} (\cot^2 p - \operatorname{cosec}^2 p)$$

$$\Rightarrow \dot{P} = -\frac{\partial H}{\partial Q} (\operatorname{cosec}^2 p - \cot^2 p)$$

$$\Rightarrow \dot{P} = -\frac{\partial H}{\partial Q} \quad (2)$$

From equation (1) and (2) we conclude that the transformation is canonical.

Examples (From: Goldstein Page 378)

Solve simple harmonic oscillator in one dimension whose Hamiltonian

$$H = \frac{p^2}{2m} + \frac{mw^2}{2} q^2$$

And generating function $F_1 = \frac{m}{2} w q^2 \cot Q$

Where m and w are constants.

Solution: Since the generating function $F_1 = F_1(q, Q)$

Therefore
$$p = \frac{\partial F_1}{\partial q} = mwq \cot Q \quad (1)$$

$$P = -\frac{\partial F_1}{\partial Q} = -\frac{mwq^2}{2} (-\operatorname{cosec}^2 Q)$$

$$P = \frac{mwq^2}{2} \operatorname{cosec}^2 Q \quad (2)$$

$$\Rightarrow q = \sqrt{\frac{2P}{mw}} \sin Q \quad \text{Putting in equation 1}$$

Examples (From: Goldstein Page 378)

$$p = \frac{\partial F_1}{\partial q} = \sqrt{2mwP} \cos Q \quad (3)$$

Since

$$H = \frac{p^2}{2m} + \frac{mw^2}{2} q^2$$

Putting eq (2) and eq (3) in above equation

$$\Rightarrow H = \frac{2mwP \cos^2 Q}{2m} + \frac{mw^2}{2} \frac{2P}{mw} \sin^2 Q$$

$$\Rightarrow H = Pw(\cos^2 Q + \sin^2 Q)$$

$$\Rightarrow H = Pw$$

Since

$$\dot{Q} = \frac{\partial H}{\partial P} = w$$

Integrating above equation $Q = wt + \alpha$

Examples (From: Goldstein Page 378)

Now Putting in equation (2)

$$q = \sqrt{\frac{2P}{m\omega}} \sin(\omega t + \alpha)$$

since

$$P = \frac{H}{\omega}$$

Therefore above equation is

$$q = \sqrt{\frac{2H}{m\omega^2}} \sin(\omega t + \alpha)$$

Since H is not exploit function of time therefore $H = E = \text{constant}$

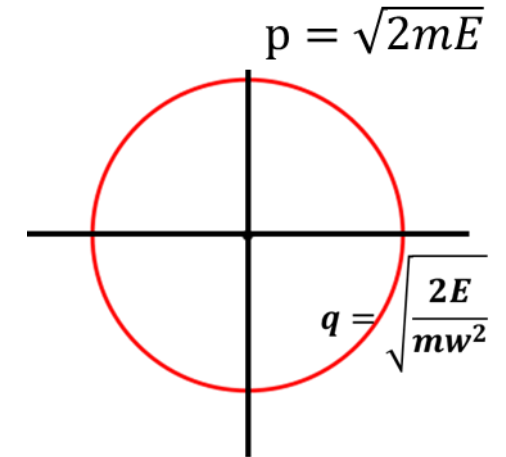
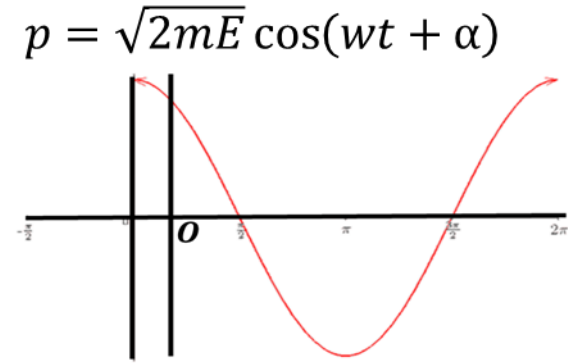
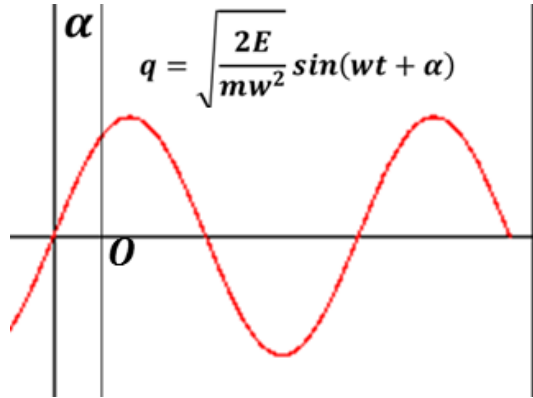
Therefore above equation is

$$q = \sqrt{\frac{2E}{m\omega^2}} \sin(\omega t + \alpha)$$

This is the one-dimensional solution of Simple Harmonic Oscillator

Examples (From: Goldstein Page 378)

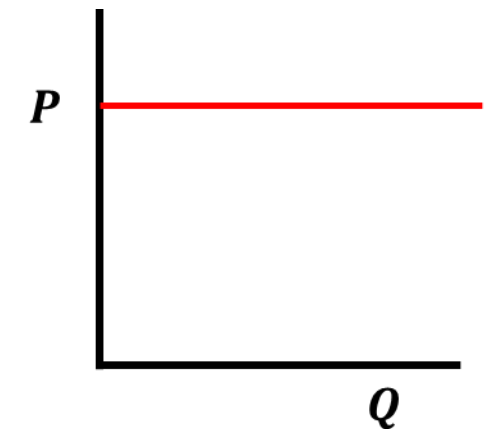
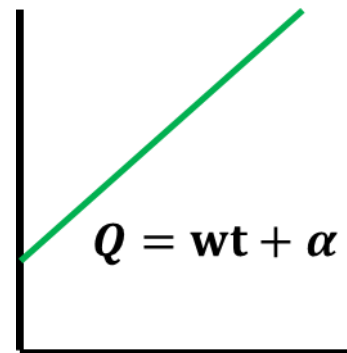
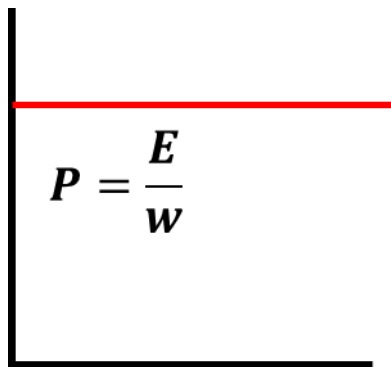
Since $q = \sqrt{\frac{2E}{m\omega^2}} \sin(\omega t + \alpha)$ & $p = \sqrt{2mE} \cos(\omega t + \alpha)$



$$P = \frac{H}{\omega} = \frac{E}{\omega}$$

&

$$Q = \omega t + \alpha$$



Examples

For what value of α and β , equations

$$Q = q^\alpha \cos \beta p \quad \text{and} \quad P = q^\alpha \sin \beta p$$

Represents a canonical transformation. Find the generating Function F_3

Solution: The transformations will be canonical if it satisfies the following conditions.

$$\dot{Q} = \frac{\partial H}{\partial P} \quad \& \quad \dot{P} = -\frac{\partial H}{\partial Q}$$

Now if we take derivative of $Q = q^\alpha \cos \beta p$

$$\dot{Q} = \alpha q^{\alpha-1} \dot{q} \cos \beta p - \beta q^\alpha \dot{p} \sin \beta p$$

And

$$\dot{q} = \frac{\partial H}{\partial p} \quad \& \quad \dot{p} = -\frac{\partial H}{\partial q}$$

$$\Rightarrow \dot{Q} = \alpha q^{\alpha-1} \frac{\partial H}{\partial p} \cos \beta p + \beta q^\alpha \frac{\partial H}{\partial q} \sin \beta p$$

Examples

$$\Rightarrow \dot{Q} = \alpha q^{\alpha-1} \frac{\partial H}{\partial P} \frac{\partial P}{\partial p} \cos \beta p + \beta q^{\alpha} \frac{\partial H}{\partial P} \frac{\partial P}{\partial q} \sin \beta p$$

$$\Rightarrow \dot{Q} = \left(\alpha q^{\alpha-1} \frac{\partial P}{\partial p} \cos \beta p + \beta q^{\alpha} \frac{\partial P}{\partial q} \sin \beta p \right) \frac{\partial H}{\partial P}$$

$$\Rightarrow \dot{Q} = [\alpha q^{\alpha-1} (\beta q^{\alpha} \cos \beta p) \cos \beta p + \beta q^{\alpha} (\alpha q^{\alpha-1} \sin \beta p) \sin \beta p] \frac{\partial H}{\partial P}$$

$$\Rightarrow \dot{Q} = [\alpha \beta q^{2\alpha-1} \cos^2 \beta p + \alpha \beta q^{2\alpha-1} \sin^2 \beta p] \frac{\partial H}{\partial P}$$

$$\Rightarrow \dot{Q} = \alpha \beta q^{2\alpha-1} [\cos^2 \beta p + \sin^2 \beta p] \frac{\partial H}{\partial P} = \alpha \beta q^{2\alpha-1} \frac{\partial H}{\partial P}$$

The transformation is canonical if

$$\alpha \beta q^{2\alpha-1} = 1$$

$$\Rightarrow q^{2\alpha-1} = 1$$

Examples

$$\Rightarrow 2\alpha - 1 = 0$$

$$\Rightarrow \alpha = 1/2 \quad \& \quad \Rightarrow \beta = 2$$

Therefore, $Q = q^{1/2} \cos 2p$ and $P = q^{1/2} \sin 2p$

Now the generating function $\frac{\partial F_3}{\partial p} = -q$
 $\Rightarrow F_3 = -qp$

Since

$$Q^2 + P^2 = q(\cos^2 2p + \sin^2 2p) = q \quad \& \quad \frac{P}{Q} = \tan 2p \Rightarrow p = \frac{1}{2} \tan^{-1} \frac{P}{Q}$$

Therefore the generating function

$$F_3 = -qp = -\frac{1}{2}(Q^2 + P^2) \tan^{-1} \frac{P}{Q}$$

Examples (Book: Classical mechanics by Takwal)

Show that the transformation is canonical

$$Q = \log(1 + q^{1/2} \cos p) \quad \text{and} \quad P = 2(1 + q^{1/2} \cos p)q^{1/2} \sin p$$

Also Show that the generating function $F_3 = -(e^Q - 1)^2 \tan p$

Solution: The transformations will be canonical if it satisfies the following conditions.

$$\dot{Q} = \frac{\partial H}{\partial P} \quad \& \quad \dot{P} = -\frac{\partial H}{\partial Q}$$

Now if we take derivative of $Q = q^\alpha \cos \beta p$

$$\dot{Q} = \frac{1}{(1+q^{1/2} \cos p)} \frac{d}{dt} (1 + q^{1/2} \cos p)$$

$$\dot{Q} = \frac{1}{(1+q^{1/2} \cos p)} \left(\frac{1}{2} q^{-1/2} \dot{q} \cos p - q^{1/2} \dot{p} \sin p \right)$$

Examples (Book: Classical mechanics by Takwal)

And
$$\dot{q} = \frac{\partial H}{\partial p} = \frac{\partial H}{\partial P} \frac{\partial P}{\partial p} \quad \& \quad \dot{p} = -\frac{\partial H}{\partial q} = -\frac{\partial H}{\partial P} \frac{\partial P}{\partial q}$$

Therefore,
$$\dot{Q} = \frac{1}{(1+q^{1/2} \cos p)} \left(\frac{1}{2} q^{-1/2} \frac{\partial H}{\partial P} \frac{\partial P}{\partial p} \cos p + q^{1/2} \frac{\partial H}{\partial P} \frac{\partial P}{\partial q} \sin p \right)$$

$$\Rightarrow \dot{Q} = \frac{1}{(1+q^{1/2} \cos p)} \left(\frac{1}{2} q^{-1/2} \frac{\partial P}{\partial p} \cos p + q^{1/2} \frac{\partial P}{\partial q} \sin p \right) \frac{\partial H}{\partial P}$$

$$\Rightarrow \dot{Q} = \frac{1}{(1+q^{1/2} \cos p)} \left(\frac{1}{2} q^{-1/2} \frac{\partial}{\partial p} (2q^{1/2} \sin p + q \sin 2p) \cos p + q^{1/2} \frac{\partial}{\partial q} (2q^{1/2} \sin p + q \sin 2p) \sin p \right) \frac{\partial H}{\partial P}$$

$$\Rightarrow \dot{Q} = \frac{1}{(1+q^{1/2} \cos p)} \left(\frac{1}{2} q^{-1/2} (2q^{1/2} \cos p + 2q \cos 2p) \cos p + q^{1/2} \left(2 \frac{1}{2} q^{-1/2} \sin p + \sin 2p \right) \sin p \right) \frac{\partial H}{\partial P}$$

$$\Rightarrow \dot{Q} = \frac{1}{(1+q^{1/2} \cos p)} \left(\cos^2 p + q^{1/2} \cos 2p \cos p + \sin^2 p + q^{1/2} \sin 2p \sin p \right) \frac{\partial H}{\partial P}$$

Examples (Book: Classical mechanics by Takwal)

$$\dot{Q} = \frac{1}{(1+q^{1/2} \cos p)} \left((\cos^2 p + \sin^2 p) + q^{1/2} (\cos 2p \cos p + \sin 2p \sin p) \right) \frac{\partial H}{\partial P}$$

$$\dot{Q} = \frac{1}{(1+q^{1/2} \cos p)} (1 + q^{1/2} \cos(2p - p)) \frac{\partial H}{\partial P}$$

$$\dot{Q} = \frac{1}{(1+q^{1/2} \cos p)} (1 + q^{1/2} \cos p) \frac{\partial H}{\partial P}$$

$$\dot{Q} = \frac{\partial H}{\partial P}$$

Similarly

$$\dot{P} = 2(1 + q^{1/2} \cos p) \left(\frac{1}{2} q^{-1/2} \dot{q} \sin p + q^{1/2} \dot{p} \cos p \right) + 2q^{1/2} \sin p \left(\frac{1}{2} q^{-1/2} \dot{q} \cos p - q^{1/2} \dot{p} \sin p \right)$$

$$\Rightarrow \dot{P} = (q^{-1/2} \sin p + \sin 2p) \dot{q} + 2(q^{1/2} \cos^2 p + q \cos 2p) \dot{p}$$

And $\dot{q} = \frac{\partial H}{\partial p} = \frac{\partial H}{\partial Q} \frac{\partial Q}{\partial p}$ & $\dot{p} = -\frac{\partial H}{\partial q} = -\frac{\partial H}{\partial Q} \frac{\partial Q}{\partial q}$

Examples (Book: Classical mechanics by Takwal)

Putting and solving we get $\dot{P} = -\frac{\partial H}{\partial Q}$ (Home work)

Hence the transformation is canonical.

$$\text{Now } \frac{\partial F_3}{\partial Q} = \frac{\partial}{\partial Q} [-(e^Q - 1)^2 \tan p]$$

$$\frac{\partial F_3}{\partial Q} = [-2(e^Q - 1)e^Q \tan p]$$

$$\frac{\partial F_3}{\partial Q} = \left[-2 \left(e^{\log(1+q^{1/2} \cos p)} - 1 \right) e^{\log(1+q^{1/2} \cos p)} \tan p \right]$$

$$\frac{\partial F_3}{\partial Q} = \left[-2(1 + q^{1/2} \cos p - 1)(1 + q^{1/2} \cos p) \tan p \right]$$

$$\frac{\partial F_3}{\partial Q} = \left[-2(q^{1/2} \cos p)(1 + q^{1/2} \cos p) \tan p \right]$$

$$\frac{\partial F_3}{\partial Q} = -\left[2(1 + q^{1/2} \cos p) q^{1/2} \sin p \right] = -P$$